Development and Maintenance of Class 395 High-speed Train for UK High Speed 1

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OVERVIEW: Hitachi supplied 174 cars to consist of 29 train sets for the Class 395 universal AC/DC high-speed trains able to transfer directly between the UK’s existing network and High Speed 1, the country’s first dedicated high-speed railway line. The Class 395 was developed by applying technologies for lighter weight and higher speed developed in Japan to the UK railway system based on the A-train concept which features a lightweight aluminum carbody and self-supporting interior module. Hitachi is also responsible for conducting operating trials to verify the reliability and ride comfort of the trains and for providing maintenance services after the trains start operation. The trains, which formally commenced commercial operation in December 2009, are helping to increase the speed of domestic services in Southeast England and it is anticipated that they will have an important role in transporting visitors between venues during the London 2012 Olympic Games.

INTRODUCTION
HIGH Speed 1 (HS1) is a new 109-km high-speed railway line linking London to the Channel Tunnel [prior to completion of the whole link, the line was known as the CTRL (Channel Tunnel Rail Link)]. Construction of the line, which is the first dedicated high-speed railway in the UK, commenced in 1998 and operation along its full length started in 2007. This cut 40 minutes off the travel time along this stretch of line for the Eurostar international train which previously ran on the UK’s existing railway network. Hitachi supplied the new Class 395 high-speed train to be able to run on both HS1 and the existing network as part of a project to improve domestic services on adjacent track as well as make more effective use of the new line (see Fig. 1).

As the contract with Hitachi’s UK customer included maintenance services, it was important that...
the trains comply with the customer’s requirements and local standards while also taking account of maintenance and LCC (life cycle cost) considerations from the train’s design stages.

This article provides an overview of the Class 395 high-speed train for the HS1 in the UK and describes its distinctive technologies and the maintenance service provided from a new maintenance depot built specifically for the train.

**EXTERIOR AND INTERIOR OVERVIEW OF CLASS 395**

**Design**

The “one motion form” design with its smooth nose-shape and low air resistance not only creates an image for the front-end of the train that is ideal for a high-speed train, it also reduces train resistance and noise. The exterior color, which was specified by the railway operator, has a dark-blue base with yellow used to highlight the front end of the train (see Fig. 1).

White is the main color used for the interior walls and ceilings. The aisle width, lighting, and arrangement of interior equipment follow a universal design that complies with the UK’s RVAR (Rail Vehicle Accessibility Regulations). The seat layout is based on two-person seats in the standard passenger compartments with single-person tip-up seats fitted in the wheelchair space in the leading car. The trains have open vestibules that are not segregated from the passenger compartments and these are fitted with draught screens that act as a windbreak (see Fig. 2).

**Basic Specifications**

Table 1 lists the main specifications and Fig. 3 shows a diagram of the train formation. The trainsets consist of six cars per trainset and both leading cars are fitted with automatic couplings with front hatches so that up to two trainsets can be coupled to allow operation with 12 cars per train. As the trainsets may be coupled or uncoupled at intermediate stations when in operation, the automatic couplings are designed to take no more than one minute to complete coupling or uncoupling.

The carbody is made of aluminum alloy and the sides, roof, and floor have a double-skin structure formed from hollow thin-wall extrusions. Further, use of FSW (friction stir welding) for the welds achieves an exterior that is light, has high strength, and minimal strain\(^1\). The trains also travel at speeds exceeding 200 km/h and the cars are made airtight.

The bogies are bolster-less and, in addition to being designed for stability when traveling on the new high-speed line and for curving performance on the existing

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**Table 1. Key Rolling Stock Specifications**

<table>
<thead>
<tr>
<th>Item</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Class</td>
<td>UK Class 395</td>
</tr>
<tr>
<td>Trainset</td>
<td>6 cars (DPT1 + MS1 + MS2 + MS3 + MS4 + DPT2)</td>
</tr>
<tr>
<td>Number of passengers</td>
<td>Standard seating: 298, priority seating: 42</td>
</tr>
<tr>
<td>Electric system</td>
<td>AC 25 kV, DC 750 V</td>
</tr>
<tr>
<td>Gauge</td>
<td>1,435 mm</td>
</tr>
<tr>
<td>Maximum speed</td>
<td>225 km/h (AC overhead line), 160 km/h (DC third rail)</td>
</tr>
<tr>
<td>Acceleration</td>
<td>0.70 m/s(^2)</td>
</tr>
<tr>
<td>Deceleration</td>
<td>Normal: 0.90 m/s(^2), emergency: 1.20 m/s(^2)</td>
</tr>
<tr>
<td>Gradient</td>
<td>25‰ (max.)</td>
</tr>
<tr>
<td>Brake control</td>
<td>Electrically operated air brake</td>
</tr>
<tr>
<td>Main converter</td>
<td>4 × IGBT converter/inverters + brake choppers per set</td>
</tr>
<tr>
<td>Main electric motors</td>
<td>16 × 210 kW sequential per set</td>
</tr>
<tr>
<td>Auxiliary power</td>
<td>3 × 110 kVA per set (3-phase 400 V AC + 110 V DC)</td>
</tr>
<tr>
<td>Carbody</td>
<td>Double-skin aluminum structure</td>
</tr>
<tr>
<td>Bogies</td>
<td>Bolster-less bogies</td>
</tr>
<tr>
<td>Air conditioning</td>
<td>Heater-type heating, ventilation, and air-conditioning unit (with internal ventilation fan)</td>
</tr>
</tbody>
</table>

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(a) Vestibule (leading car)  
(b) Standard passenger salon (intermediate car)  
(c) Driving cab  
(d) Bogie

*Fig. 2—Vestibule, Passenger Salon, Driving Cab, and Bogie. The open vestibules (a) are not segregated from the passenger salon and the seat layout is based on two-person seats (b). The driving cab was reviewed by train drivers for its ease-of-use and visibility and this feedback was incorporated into the design (c). The design of the bogies considered stability when traveling on the new high-speed line and cornering characteristics on the existing line (d).*
crew, passengers, and others in the event of a collision. To comply, the front-end of the Class 395 and the vehicle-end of each car adopted crashworthy structures that satisfy TSi (Technical Specifications for Interoperability) and the UK’s RgS (Railway Group Standards). In the event of such an accident, the concept on which the design is based is that the crashworthy structures will crumple to absorb the crash energy and prevent the passenger and driver compartments from being crushed, thereby forming a survival space for the passengers and crew\(^{3}\). The driving cab, seats, tables, and other interior fittings have also been designed to comply with the crash safety requirements stipulated by the RgS, ATOC (Association of Train Operating Companies), and other standards.

For fire safety, regulations are also stipulated by a number of different standards including BS (British Standards), RgS, and ATOC. Apart from a small number of exceptions, all non-metallic materials used in the cars were required to satisfy BS fire retardancy rules and appropriate account was taken of this requirement when selecting the internal materials for the Class 395. The floor structure consists of carpet, floor boards and an underframe, and the overall structure of the vehicle-end including the insulation and inter-vehicle doors was designed to ensure fire resistance.

In addition to being subjected to detailed numerical analysis, unit testing, and other forms of evaluation\(^{4}\), the performance of the structure of the Class 395 was

**DISTINCTIVE TECHNOLOGIES OF CLASS 395**

In addition to the requirements of the UK customer, ensuring the rolling stock were compatible with the standards, operating practices, infrastructure, and other aspects of the local railway system were also important issues for the Class 395. This meant that several design features intended for Japan were not applicable. The following sections describe some representative examples of new technology development and testing carried out specifically for the Class 395.

**Creating a Safe and Comfortable Vehicle Environment**

Many of the standards relating to collision, strength, fire resistance, noise, and similar were very different to those that apply in Japan\(^{2}\).

For example, cultural factors in Europe have led to stringent collision safety rules to ensure the safety of crew, passengers, and others in the event of a collision.

The driving cab houses the master controller along with various switches and monitors which surround the driver’s seat, and also incorporates a crash pad that was optimized using the result of crash simulations analysis. An early mockup of the driving cab was fabricated so that it could be assessed by the drivers for ease of operation of switches and exterior visibility, and the results of this were reflected in the cab design.

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**Fig. 3—Train Formation.**

The trainset which always consists of six cars has a total length of about 122 m. Both leading cars are fitted with automatic couplings with front hatches so that up to two trainsets can be coupled to allow operation with 12 cars per train.
verified using various different tests including crash testing of full-size specimens, interior crash testing, static load testing, and fire-resistance testing, as indicated by the representative examples shown in Fig. 4. The trains were also subject to an audit by the UK Notified Body (NoBo) and were certified as complying with the standards.

Compatibility with UK Rail Infrastructure

(1) Gauging

As the existing UK railway lines did not have any static gauge that were applicable to the new vehicle, the manufacturer needed to determine the vehicle size based on the clearance from the line’s stationary facilities and part of the certification process was to demonstrate that the train would not collide with these facilities. For this reason, a dynamic analysis of the lateral movement of the rolling stock was performed and the results were checked against the actual data for the stationary facilities so that the vehicle sizes and bogie suspension could be designed to ensure that sufficient clearance was available.

(2) Vehicle dynamics

The Class 395 is what is known in Japan as a high-speed existing line direct transfer train and needs to be able to negotiate the sharp curves smoothly on conventional line while also operating stably at a maximum speed of 225 km/h on the high-speed line. To satisfy this requirement, the vehicle dynamics simulation shown in Fig. 5 was used to optimize the bogie suspension to achieve stability, ride comfort, and curving performance. Also, to comply with UK standards, it was necessary to perform the special sway test shown in Fig. 6 (a) to provide a verification of the analysis of body lateral movement. As shown in Fig. 6 (b) the results of testing and analysis show good agreement for large displacements indicating that the analysis of body lateral movement provided sufficient prediction accuracy.

(3) Pressure variations in tunnels

In the UK and other European countries, the pressure variations inside and outside the vehicle when traveling through a tunnel must be kept within the standard of 10 kPa. This rule exists to minimize the effect on the tunnel walls by minimizing the pressure variations to which they are subjected, and also for considerations of passenger comfort. A computational fluid dynamics was conducted to verify the level of these pressure variations in tunnels.

It is known that pressure variations in tunnels become greater when two trains are passing in opposite directions. Fig. 7 shows the results of an analysis conducted using a three-dimensional model of this case
when two trains traveling in opposite directions pass each other in a tunnel. The pressure variations in the tunnel were estimated from the results of this analysis to confirm that they would remain below the limit. In practice, the actual pressure variations will depend on the cross section, shape, and other characteristics of the tunnel, passing train, and other elements. To perform the assessment efficiently, therefore, all of the tunnels along the HS1 were tested using the single-dimension characteristic curve method and the computational fluid dynamics using a three-dimensional model only used on the worst cases to confirm that they remain within the limit.

Train Operation Control Suitable for Operating Practices Specification to UK

(1) TMS overview

The TMS (train management system) is a system for providing the functions required by the crew and maintenance staff such as monitoring equipment status, equipment controlling, and self-diagnostics of equipment through the exchange of information via inter-vehicle trunk communications and communications with the on-board equipment.

The TMS for the Class 395 was developed based on the standard ATI-C(7) (autonomous decentralized train integration system with control command transmission) which uses fail-safe trunk communications with redundancy backup and obtained an SIL 2 (safety integrity level 2) safety rating under the IEC61508 standard due to the improved reliability of the SDO (selective door opening) function.

Fig. 8 shows a system block diagram of the TMS for the Class 395. The central unit located in the front-end vehicle and terminal units in each of the intermediate vehicle are connected together via a trunk transmission line with a communication speed of 3.2 Mbit/s and a redundant ladder topology. In addition to DI's (digital inputs) that receive the status of the master controller and other switches, power supply, and other components and DO's (digital outputs) that transmit signals such as the door release as one of the SDO function, serial communication is also used to handle communications with key equipment for monitoring and controlling. Also, touch-panel LCDs (liquid crystal displays) are used in the cab to display this status information, enter commands, and so on.

(2) SDO function

On conventional UK trains, it is common practice for the passengers to operate the open/close buttons...
on each door after the crew use the “release operation” to unlock the doors. As dealing with stations where the platform is shorter than the length of the train is a regular occurrence, if all the doors are unlocked there is a risk of passengers inadvertently opening a door where there is no platform and falling from the train and therefore a function is needed to select which doors are safe to open based on the length of the platform at each station. As a requirement in the UK is to avoid as far as possible operations that require the crew to make decisions, an SDO function that can automatically select which doors are safe to open at each station is required.

As the SDO function determines which doors to unlock based on the current station, the function to detect which station the train has stopped at is critical. The SDO function fitted in existing trains uses GPS (global positioning system) to identify the station, but the problem with this approach is that it fails to work correctly if the GPS signal cannot be received such as in roofed stations. To deal with this problem, the station detection method in the SDO function on the Class 395, in addition to using GPS, also independently determines the station based on position information estimated from the train speed and then compares the results of the two methods. Door release control is then performed based on this station identification, railway line, and other information. The four standard cases for door release control are as follows.

(a) When traveling on HS1

As all of the stations along the HS1 high-speed line are guaranteed to have platforms longer than the maximum 12 cars that make up the train in the coupled configuration, station identification is not performed and all doors are unlocked when the train stops. The station checking screen appears on the driver’s display unit when the door locks are released to display the current station and lock/release status of each door to the crew (see Fig. 9).

(b) Station identification results match

When traveling on a conventional line, if the stations detected by the GPS and distance traveled methods are the same, door release control operates on the assumption that the station identification is correct.

(c) Station identification results do not match

When traveling on a conventional line, if the stations detected by the GPS and distance-traveled methods are not the same, whether because the GPS signal cannot be received, the route has not been entered, or some other reason, the possible stations identified by the distance-traveled method are displayed on screen and the driver prompted to confirm the correct station. Door release control then proceeds based on the driver’s selection.

(d) Station identification is unavailable

When traveling on a conventional line, if neither system is able to work because both the GPS signal cannot be received and the route has not been entered, or for some other reason, door release control is unable to function because the TMS has no information by which to identify the station. In this case, a screen containing a list of all stations is displayed and the driver selects the station to allow door release control to proceed.

MAINTENANCE

Consideration of Maintainability

As the terms of this project also included maintenance, maintenance considerations were included in the design from the earliest investigation stages.

As Hitachi did not have any past experience with rolling stock maintenance, an effort was made to visit railway operators in Japan to observe and learn maintenance techniques. The results of this initiative were collated in the design requirements to provide the designers with guidelines on maintainability. The design then proceeded in accordance with this design requirements document.

Construction of Maintenance Depot

The design and construction of the maintenance depot took place in parallel with the design and
manufacture of the rolling stock, and the know-how needed to establish a maintenance depot was obtained with the cooperation of Japanese railway operators and reflected in the design of the actual depot. The following lists the factors taken into consideration in the depot construction.

1. Layout specifically designed to suit the Class 395
2. Optimization study of workflow
3. Track layout designed for trouble-free shunting
4. Encourage workforce minimization
5. Establish data management practices based on information technology

Fig. 10 shows a diagram of the maintenance depot layout. Trains enter from point A where measurements are taken of the state of consumable items such as brake pads using automatic measurement equipment. This information is passed via a network to the depot management system where it is recorded and utilized in maintenance work. Next, the train is parked on stabling siding B and the track layout also allows it to move to shed C without needing a switchback. Shed C is designed in such a way that it can be used for all necessary inspection and repair work. Distribution store D is located next to shed C to optimize workflows by allowing the convenient movement of goods. The spacing between shed tracks is also designed to ensure adequate access for loading and unloading by forklift.

**Maintenance Plan**

Unlike Japan, there are no clearly determined standards for train maintenance established by law in the UK. Instead, the approach used is to formulate a maintenance plan for each train and to have this approved by the relevant auditing agency.

The Class 395 is a high-speed train with a maximum speed of 225 km/h and its maintenance plan was formulated based on the maintenance of Japanese Shinkansen trains. Table 2 lists the maintenance intervals for the Class 395 and summarizes what these involve.

**Current Maintenance Situation**

Commercial operation formally commenced in December 2009 with the trains being maintained in accordance with the plan and dispatched to the operating company on a daily basis. Overhauls are due to start during 2010 and, with the initial overhaul expected to be completed without incident, detailed planning is currently underway.

**CONCLUSIONS**

This article has given an overview of the Class 395 high-speed train for UK HSI which is the first high-speed train from a Japanese rolling stock manufacturer to be supplied to Europe, and described its distinctive technologies and maintenance.

The Class 395 commenced commercial operation on-schedule in December 2009 and is helping increase the speed of domestic services in Southeast England. The train is also winning a good reputation for its ride quality and design.
Hitachi has added advanced technologies developed specifically for the Class 395 to its technologies for lighter weight and faster speed built up over past years, and its intention is to develop more comfortable and attractive trains suitable for European railway systems and to supply these together with maintenance services.

REFERENCES

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